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L15 L14 and l6

2 L15

L14 l10 or l12 or l13

59 L14

DB=USPT; THES=ASSIGNEE; PLUR=YES; OP=OR

L13 (3648029 | 3786497 | 4121204 | 3921166 | T904088)!
 [PN]

4 L13

*DB=PGPB,USPT,DWPI; THES=ASSIGNEE; PLUR=YES;
OP=OR*

L12 ("20040263494"| "20050137765"| "20050141997"|
"4221975"| "US20050137765A"| "WO 200288905A") 9 L12
[ABPN1,NRPN,PN]

*DB=PGPB,USPT,USOC,EPAB,JPAB,DWPI,TDBD;
THES=ASSIGNEE; PLUR=YES; OP=OR*

L11 19 6 L11

*DB=PGPB,USPT,DWPI; THES=ASSIGNEE; PLUR=YES;
OP=OR*

L10 ("20040263494"| "20050137765"| "20050141997"|
"4221975"| "US20050137765A"| "WO 200288905A") 46 L10
[URPN]

*DB=PGPB,USPT,USOC,EPAB,JPAB,DWPI,TDBD;
THES=ASSIGNEE; PLUR=YES; OP=OR*

L9 20040263494 or 15 6 L9

L8 L7 and (vehicle or car or automobile) 1 L8

L7 L6 not 14 13 L7

L6 (prox\$ near4 sens\$) and (sequen\$ with pattern\$) and
(control\$ adj5 (device or apparatus or component or
system)) and (activat\$ near5 sequenc\$) 13 L6

L5 (prox\$ near2 sens\$) and (sequent\$ with pattern\$) and
(control\$ adj3 (device or apparatus or component or
system)) and (activat\$ near4 sequenc\$) 4 L5

L4 (prox\$ near2 sens\$) and (sequent\$ with pattern\$) and
(control\$ adj3 (device or apparatus or component or
system)) and (activat\$ near4 sequenc\$) and ((decre\$ or
incre\$) near3 direction\$) 0 L4

L3 led and (slid\$ with (control\$ or activat\$)) and (prox\$
near2 sens\$) and (sequent\$ with pattern\$) and (control\$
adj3 (device or apparatus or component or system)) and
(activat\$ near4 sequenc\$) and ((decre\$ or incre\$) near3
direction\$) 0 L3

(slid\$ with (control\$ or activat\$)) and (prox\$ near2
sens\$) and (sequent\$ with pattern\$) and (control\$ adj3

<u>L2</u>	(device or apparatus or component or system)) and (activat\$ near4 sequenc\$) and ((decre\$ or incre\$) near3 direction\$) and @ad<=20031219	0	<u>L2</u>
<u>L1</u>	20050137765	2	<u>L1</u>

END OF SEARCH HISTORY

Results for "((sequen* <near/4> pattern*) <and> (prox* <near/4> sens*) <and> ((switch* ..."

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- ☐ 1. **EMI emissions of modern PWM AC drives**
Skibinski, G.L.; Kerkman, R.J.; Schlegel, D.;
[Industry Applications Magazine, IEEE](#)
Volume 5, Issue 6, Nov.-Dec. 1999 Page(s):47 - 80
Digital Object Identifier 10.1109/2943.798337
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- ☐ 2. **Behavior analysis and training-a methodology for behavior engineering**
Colombetti, M.; Dorigo, M.; Borghi, G.;
[Systems, Man and Cybernetics, Part B, IEEE Transactions on](#)
Volume 26, Issue 3, June 1996 Page(s):365 - 380
Digital Object Identifier 10.1109/3477.499789
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- ☐ 3. **Particle-beam fabrication and in situ processing of integrated circuits**
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[Proceedings of the IEEE](#)
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- ☐ 4. **Extraction of ocean wave parameters from HF backscatter received by a four-element antenna**
Gill, E.W.; Walsh, J.;
[Oceanic Engineering, IEEE Journal of](#)
Volume 17, Issue 4, Oct. 1992 Page(s):376 - 386
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- ☐ 5. **Flexible syntactic matching of curves and its application to automatic hierarchical of silhouettes**
Gdalyahu, Y.; Weinshall, D.;
[Pattern Analysis and Machine Intelligence, IEEE Transactions on](#)
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Digital Object Identifier 10.1109/34.817410
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- ☐ 6. **Automatic gait recognition based on statistical shape analysis**

Liang Wang; Tieniu Tan; Weiming Hu; Huazhong Ning;
[Image Processing, IEEE Transactions on](#)
Volume 12, Issue 9, Sept. 2003 Page(s):1120 - 1131
Digital Object Identifier 10.1109/TIP.2003.815251
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- ☐ 7. **Web mining in soft computing framework: relevance, state of the art and future directions**
Pal, S.K.; Talwar, V.; Mitra, P.;
[Neural Networks, IEEE Transactions on](#)
Volume 13, Issue 5, Sep 2002 Page(s):1163 - 1177
Digital Object Identifier 10.1109/TNN.2002.1031947
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- ☐ 8. **Linguistic analysis of experimental curves**
Mottl, V.V.; Muchnik, I.B.;
[Proceedings of the IEEE](#)
Volume 67, Issue 5, May 1979 Page(s):714 - 736
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- ☐ 9. **Automatic locomotion design and experiments for a Modular robotic system**
Kamimura, A.; Kurokawa, H.; Yoshida, E.; Murata, S.; Tomita, K.; Kokaji, S.;
[Mechatronics, IEEE/ASME Transactions on](#)
Volume 10, Issue 3, June 2005 Page(s):314 - 325
Digital Object Identifier 10.1109/TMECH.2005.848299
[AbstractPlus](#) | Full Text: [PDF\(856 KB\)](#) IEEE JNL
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- ☐ 10. **Unbalance and harmonics detection in induction motors using an optical fiber sensor**
Corres, J.M.; Bravo, J.; Arregui, F.J.; Matias, I.R.;
[Sensors Journal, IEEE](#)
Volume 6, Issue 3, June 2006 Page(s):605 - 612
Digital Object Identifier 10.1109/JSEN.2006.874441
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- ☐ 11. **Force interaction and allocation for the legs of a walking vehicle**
Klein, C.; Tae-Sang Chung;
[Robotics and Automation, IEEE Journal of \[legacy, pre - 1988\]](#)
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- ☐ 12. **The application of neural networks to fuel processors for fuel-cell vehicles**
Iwan, L.C.; Stenget, R.F.;
[Vehicular Technology, IEEE Transactions on](#)
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Digital Object Identifier 10.1109/25.917898
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- ☐ 13. **Shielding and electrical performance of silicon detector supermodules**
Ely, R.P.; Weber, M.; Zimmermann, S.; Rong-Shyang Lu; Lujan, P.J.;
[Nuclear Science, IEEE Transactions on](#)
Volume 52, Issue 5, Part 3, Oct. 2005 Page(s):1892 - 1898
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- ☐ **14. HMM based online handwriting recognition**
Jianying Hu; Brown, M.K.; Turin, W.;
[Pattern Analysis and Machine Intelligence, IEEE Transactions on](#)
Volume 18, Issue 10, Oct. 1996 Page(s):1039 - 1045
Digital Object Identifier 10.1109/34.541414

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- ☐ **15. Modeling context-aware e-learning scenarios**
Derntl, M.; Hummel, K.A.;
[Pervasive Computing and Communications Workshops, 2005. PerCom 2005 Workshops](#)
[International Conference on](#)
8-12 March 2005 Page(s):337 - 342
Digital Object Identifier 10.1109/PERCOMW.2005.60

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- ☐ **16. A hierarchical system structure for coordinated control of industrial manipulators**
Kang Shin; Malin, S.;
[Robotics and Automation, Proceedings, 1984 IEEE International Conference on](#)
Volume 1, Mar 1984 Page(s):609 - 619

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- ☐ **17. Dynamics of projective adaptive resonance theory model: the foundation of PART**
Yongqiang Cao; Jianhong Wu;
[Neural Networks, IEEE Transactions on](#)
Volume 15, Issue 2, March 2004 Page(s):245 - 260
Digital Object Identifier 10.1109/TNN.2004.824261

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- ☐ **18. Distributed Data Streams Indexing using Content-Based Routing Paradigm**
Bulut, A.; Singh, A.K.; Vitenberg, R.;
[Parallel and Distributed Processing Symposium, 2005. Proceedings, 19th IEEE Internat](#)
04-08 April 2005 Page(s):94 - 94
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- ☐ **19. Amplitude spectrum-based gait recognition**
Guoying Zhao; Rui Chen; Guoyi Liu; Hua Li;
[Automatic Face and Gesture Recognition, 2004. Proceedings, Sixth IEEE International C](#)
17-19 May 2004 Page(s):23 - 28
Digital Object Identifier 10.1109/AFGR.2004.1301504

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- ☐ **20. Experimental validation of pulse contour methods for estimating stroke volume at**
Yinghong Yu; Jiang Ding; Lili Liu; Salo, R.; Spinelli, J.; Tockman, B.; Pochet, T.; Auricchi;
[Engineering in Medicine and Biology Society, 1998. Proceedings of the 20th Annual Inter](#)
[Conference of the IEEE](#)
29 Oct.-1 Nov. 1998 Page(s):401 - 404 vol.1
Digital Object Identifier 10.1109/IEMBS.1998.745928

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L4: Entry 1 of 1

File: DWPI

Dec 7, 2006

DERWENT-ACC-NO: 2007-137409

DERWENT-WEEK: 200714

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TITLE: Satellite positioning system's e.g. global positioning system, receiver position locating method for use with e.g. cellular telephone, involves obtaining range-rate measurements at receiver with respect to set of satellites

INVENTOR: DIGGELEN, F V; VAN DIGGELEN, F

PATENT-ASSIGNEE: DIGGELEN F V (DIGGI), GLOBAL LOCATE INC (GLOBN)

PRIORITY-DATA: 2005US-0142824 (June 1, 2005)

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PATENT-FAMILY:

PUB-NO	PUB-DATE	LANGUAGE	PAGES	MAIN-IPC
<input type="checkbox"/> WO 2006130515 A2	December 7, 2006	E	000	
<input type="checkbox"/> US 20060273954 A1	December 7, 2006		013	G01S005/14

DESIGNATED-STATES: AE AG AL AM AT AU AZ BA BB BG BR BW BY BZ CA CH CN CO CR CU CZ DE DK DM DZ EC EE EG ES FI GB GD GE GH GM HR HU ID IL IN IS JP KE KG KM KN KP KR KZ LC LK LR LS LT LU LV LY MA MD MG MK MN MW MX MZ NA NG NI NO NZ OM PG PH PL PT RO RU SC SD SE SG SK SL SM SY TJ TM TN TR TT TZ UA UG US UZ VC VN YU ZA ZM ZW AT BE BG BW CH CY CZ DE DK EA EE ES FI FR GB GH GM GR HU IE IS IT KE LS LT LU LV MC MW MZ NA NL OA PL PT RO SD SE SI SK SL SZ TR TZ UG ZM ZW

APPLICATION-DATA:

PUB-NO	APPL-DATE	APPL-NO	DESCRIPTOR
WO2006130515A2	May 26, 2006	2006WO-US20568	
US20060273954A1	June 1, 2005	2005US-0142824	

INT-CL (IPC): G01S 5/14

ABSTRACTED-PUB-NO: US20060273954A

BASIC-ABSTRACT:

NOVELTY - The method involves measuring fractional pseudoranges from a remote receiver to a set of satellites, and obtaining an initial position at the remote receiver. The position of the remote receiver is computed using the fractional pseudoranges and the initial position. Range-rate measurements at the remote

receiver are obtained with respect to a set of satellites by obtaining Doppler measurements with respect to the set of satellites. The position is validated using the range-rate measurements.

DETAILED DESCRIPTION - An INDEPENDENT CLAIM is also included for an apparatus for locating a position comprising a satellite signal receiver for measuring fractional pseudoranges to a set of satellites and for obtaining range-rate measurements with respect to the set of satellites.

USE - Used for locating a position of a receiver of a satellite positioning system (SPS) e.g. global positioning system (GPS), wide area augmentation system (WAAS), European GALILEO system, SBAS, and Russian GLONASS system, that is connected with a server via a network e.g. wireless network such as a cellular telephone network, and a wired network such as Internet, in a position location system that is utilized with a mobile or wireless device e.g. cellular telephone, pager, laptop computer, and personal digital assistant (PDA).

ADVANTAGE - The method effectively performs a validation of the position of the receiver in the satellite position system.

DESCRIPTION OF DRAWING(S) - The drawing shows a flow diagram depicting an embodiment of a method for locating a position of a remote receiver.

ABSTRACTED-PUB-NO: US20060273954A

EQUIVALENT-ABSTRACTS:

CHOSEN-DRAWING: Dwg.2/5

DERWENT-CLASS: W06

EPI-CODES: W06-A03A5C;

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L15: Entry 1 of 2

File: PGPB

Dec 30, 2004

PGPUB-DOCUMENT-NUMBER: 20040263494

PGPUB-FILING-TYPE: new

DOCUMENT-IDENTIFIER: US 20040263494 A1

TITLE: Location sensitive display device, system, and method of providing animation sequences

PUBLICATION-DATE: December 30, 2004

INVENTOR-INFORMATION:

NAME	CITY	STATE	COUNTRY
Poor, Kyle W.	Orlando	FL	US
Holzberg, Roger S.	Burbank	CA	US
Dietz, Paul H.	Hopkinton	MA	US
Stein, Lawrence P.	Windermere	FL	US
Swirsky, Robert	Sunnyvale	CA	US

US-CL-CURRENT: 345/204

Full	Title	Citation	Front	Review	Classification	Date	Reference	Sequences	Attachments	Claims	KWIC	Draw. D
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☐ **2. Document ID: US 4221975 A**

L15: Entry 2 of 2

File: USPT

Sep 9, 1980

US-PAT-NO: 4221975

DOCUMENT-IDENTIFIER: US 4221975 A

TITLE: Touch activated controller and method

Full	Title	Citation	Front	Review	Classification	Date	Reference	Sequences	Attachments	Claims	KWIC	Draw. D
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